



Mathematical Foundation of Fluid Mechanics

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Outline of the lecture

- Conservation of transportable quantities
- The general form of the equations
- Parabolic-elliptic and hyperbolic equations
- The choice of dependent and independent variables
- Boundary conditions
- The treatment of complex geometry
- The first steps



Conservation laws

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Conservation of mass

Conservation of momentum

Conservation of energy (1_{st} law of Thermodynamics)

Conservation of species

Second Law of Thermodynamics

-
- Each of the above equations has one transportable quantity as dependent variable and
 - every equation expresses the balance of various transport mechanisms



Balance of transport mechanisms

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The temporal rate of change of a transportable quantity per volume

=

transport through convection

+

transport through diffusion

+

production or destruction of the quantity



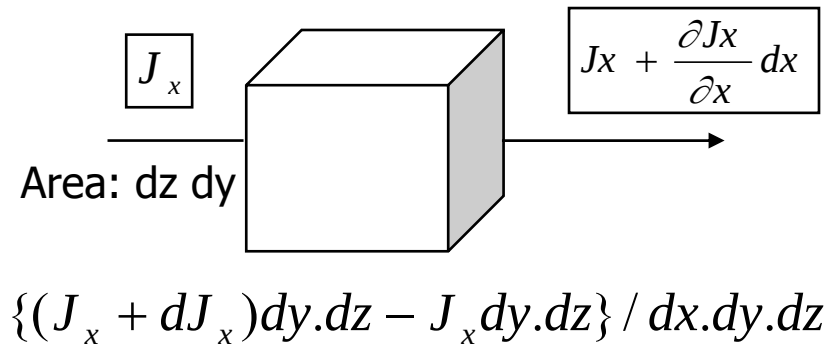
Convective transport of variable

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$$\vec{J} = \rho \vec{V} \Phi$$

Components J_x, J_y, J_z

$$J_x = \rho u \Phi, J_y = \rho v \Phi, J_z = \rho w \Phi$$



•Balance of convective transport

$$\text{div } \vec{J} = \frac{\partial J_x}{\partial x} + \frac{\partial J_y}{\partial y} + \frac{\partial J_z}{\partial z} \quad \text{per unit volume}$$



Basic Diffusion laws:

- Newton's law for "diffusion of momentum"
- Fourier's law for "diffusion of heat"
- Fick's law for "diffusion of species"

$$\tau_{ij} = \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right), \quad q = -k \nabla T, \quad q_c = -\frac{k}{Sc} \nabla C$$

All Diffusion laws are of the gradient type

$$\vec{D} = -\Gamma_{\varphi} \text{grad } \Phi$$

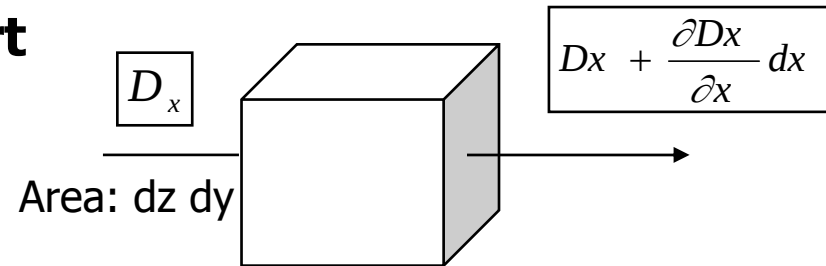


Diffusive transport/2

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Balance of diffusive transport

$$\text{div} \vec{D} = -\text{div}(\Gamma_{\phi} \text{grad} \Phi)$$



Combined convective and diffusive transport

$$\begin{aligned} \text{div}(\vec{J} + \vec{D}) &= \text{div}(\rho \vec{V} \Phi - \Gamma_{\phi} \text{grad} \Phi) \\ &= \text{div}(\rho \vec{V} \Phi) - \text{div}(\Gamma_{\phi} \text{grad} \Phi) \end{aligned}$$



Production and destruction terms

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examples of such terms S_ϕ

- **-grad p**

Body forces as

- **Coriolis forces in atmospheric flows,**
- **buoyant forces,**
- **centrifugal forces,**
- **electrostatic forces**
- **volume or area sources of heat**
- **Kinetic heating**
- **phase changes**
- **chemical reactions**



General form of the balance equation

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$$\frac{\partial(\rho\Phi)}{\partial t} + \text{div}(\rho \vec{V} \Phi - \Gamma_{\Phi} \text{grad} \Phi) = S_{\Phi}$$

net rate of change

convection

diffusion

source

- div and grad expressed on various coordinate systems
i.e. Cartesian, Curvilinear orthogonal, curvilinear, polar



Choice of dependent variables & coordinate system

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u, v, w, p, T

Ω, ψ (2D)

Cartesian velocities & Cartesian coordinates

Contravariant velocities & Curvilinear

Orthogonal or not coordinates

Cartesian velocities & Curvilinear coordinates

Solution in physical or transformed space

Need for creating curvilinear body fitted grid



Εξισώσεις διατήρησης μάζας (καρτεσιανό σύστημα συντεταγμένων)

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$$\frac{D\rho}{Dt} + \rho \nabla \cdot \vec{V} = 0 \quad (\text{μη συντηρητική μορφή})$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{V}) = 0 \quad (\text{συντηρητική μορφή})$$



Νόμοι διατήρησης ορμής (μη συντηρητική έκφραση)

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$$\rho \frac{Du}{Dt} = -\frac{\partial P}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + \rho f_x$$

x-συνιστώσα ορμής

$$\rho \frac{Dv}{Dt} = -\frac{\partial P}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + \rho f_y$$

y-συνιστώσα ορμής

$$\rho \frac{Dw}{Dt} = -\frac{\partial P}{\partial z} + \frac{\partial \tau_{zx}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} + \rho f_z$$

z-συνιστώσα ορμής

Ολική
παράγωγος

Κλίση πίεσης

Διατμητικές τάσεις

Εξωτερικές δυνάμεις



Εξισώσεις ορμής (συντηρητική έκφραση)

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$$\frac{\partial(\rho u)}{\partial t} + \nabla \cdot (\rho u \vec{V}) = -\frac{\partial P}{\partial x} + \frac{\partial \tau_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + \rho f_x \quad \text{x-συνιστώσα ορμής}$$

$$\frac{\partial(\rho v)}{\partial t} + \nabla \cdot (\rho v \vec{V}) = -\frac{\partial P}{\partial y} + \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \tau_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + \rho f_y \quad \text{y-συνιστώσα ορμής}$$

$$\frac{\partial(\rho w)}{\partial t} + \nabla \cdot (\rho w \vec{V}) = -\frac{\partial P}{\partial z} + \frac{\partial \tau_{zy}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \tau_{zz}}{\partial z} + \rho f_z \quad \text{z-συνιστώσα ορμής}$$



Εξίσωση διατήρησης ενέργειας (μη συντηρητική έκφραση)

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$$\begin{aligned} \rho \frac{D}{Dt} \left(e + \frac{V^2}{2} \right) = & \rho \dot{q} + \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) \\ & - \frac{\partial(uP)}{\partial x} - \frac{\partial(vP)}{\partial y} - \frac{\partial(wP)}{\partial z} + \frac{\partial(u\tau_{xx})}{\partial x} + \frac{\partial(u\tau_{yx})}{\partial y} + \\ & + \frac{\partial(u\tau_{zx})}{\partial z} + \frac{\partial(v\tau_{xy})}{\partial x} + \frac{\partial(v\tau_{yy})}{\partial y} + \frac{\partial(v\tau_{zy})}{\partial z} + \\ & + \frac{\partial(w\tau_{xz})}{\partial x} + \frac{\partial(w\tau_{yz})}{\partial y} + \frac{\partial(w\tau_{zz})}{\partial z} + \rho \vec{f} \cdot \vec{V} \end{aligned}$$

$$\rho \frac{D}{Dt} \left(e + \frac{V^2}{2} \right) = \frac{\partial}{\partial t} \left[\rho \left(e + \frac{V^2}{2} \right) \right] + \nabla \cdot \left[\rho \left(e + \frac{V^2}{2} \right) \vec{V} \right] \quad \text{(συντηρητική έκφραση)}$$



Ορθές διατμητικές τάσεις

$$\begin{aligned} \tau_{xx} &= \frac{2\mu}{3} \left(2 \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z} \right) & \tau_{yy} &= \frac{2\mu}{3} \left(2 \frac{\partial v}{\partial y} - \frac{\partial u}{\partial x} - \frac{\partial w}{\partial z} \right) & \tau_{zz} &= \frac{2\mu}{3} \left(2 \frac{\partial w}{\partial z} - \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right) \\ \tau_{xy} &= \mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) & \tau_{yz} &= \mu \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) & \tau_{xz} &= \mu \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right) \end{aligned}$$



Εξίσωση μεταφοράς εσωτερικής ενέργειας

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Προκύπτει από την εξίσωση διατήρησης της ενέργειας

$$\rho \frac{De}{Dt} = \rho \dot{q} + \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} \right) + \frac{\partial}{\partial y} \left(k \frac{\partial T}{\partial y} \right) + \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right)$$

$$- P \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \tau_{xx} \frac{\partial u}{\partial x} + \tau_{yx} \frac{\partial u}{\partial y} + \tau_{zx} \frac{\partial u}{\partial z}$$

$$+ \tau_{xy} \frac{\partial v}{\partial x} + \tau_{yy} \frac{\partial v}{\partial y} + \tau_{zy} \frac{\partial v}{\partial z}$$

$$+ \tau_{xz} \frac{\partial w}{\partial x} + \tau_{yz} \frac{\partial w}{\partial y} + \tau_{zz} \frac{\partial w}{\partial z}$$

$$\rho \frac{De}{Dt} = \rho \dot{q} + \nabla \cdot (k \nabla T) - P (\nabla \cdot \vec{V}) + \mu \Phi$$

$$\Phi = \left[2 \left(\frac{\partial u}{\partial x} \right)^2 + 2 \left(\frac{\partial v}{\partial y} \right)^2 + 2 \left(\frac{\partial w}{\partial z} \right)^2 + \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right)^2 \right] -$$

$$- \frac{2}{3} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2$$

Φ συνάρτηση απορρόφησης)



Εξίσωση μεταφοράς εντροπίας

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$$d e = T d S - p d \left(\frac{1}{\rho} \right) \quad \rho \frac{D s}{D t} = \frac{\rho}{T} \frac{D e}{D t} - \frac{P}{\rho T} \frac{D \rho}{D t}$$

$$\rho \frac{D s}{D t} = \frac{1}{T} \nabla \cdot (k \nabla T) + \frac{\mu}{T} \Phi$$

$$\rho \frac{D s}{D t} = \nabla \cdot \left(\frac{k}{T} \nabla T \right) + S_{gen}'''$$

$$S_{gen}''' = \frac{k}{T^2} \left[\left(\frac{\partial T}{\partial x} \right)^2 + \left(\frac{\partial T}{\partial y} \right)^2 + \left(\frac{\partial T}{\partial z} \right)^2 \right] + \frac{\mu}{T} \Phi \left(\frac{\text{watt}}{\text{m}^3} \text{K} \right)$$



Μητρική μορφή εξισώσεων διατήρησης

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$$\frac{\partial U}{\partial t} + \frac{\partial F}{\partial x} + \frac{\partial G}{\partial y} + \frac{\partial H}{\partial z} = J$$

$$U = \left\{ \begin{array}{l} \rho \\ \rho u \\ \rho v \\ \rho w \\ \rho \left(e + \frac{V^2}{2} \right) \end{array} \right\}, \quad F = \left\{ \begin{array}{l} \rho u \\ \rho u^2 + P - \tau_{xx} \\ \rho v u - \tau_{xy} \\ \rho w u - \tau_{xz} \\ \left(\rho \left(e + \frac{V^2}{2} \right) u + P u - k \frac{\partial T}{\partial x} - u \tau_{xx} - v \tau_{xy} - w \tau_{xz} \right) \end{array} \right\}$$



Μητρώα G,H,J

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$$G = \left\{ \begin{array}{l} \rho v \\ \rho u v - \tau_{yz} \\ \rho v^2 + P - \tau_{yy} \\ \rho w v - \tau_{yz} \\ \rho \left(e + \frac{V^2}{2} \right) v + P v - k \frac{\partial T}{\partial y} - u \tau_{yx} - v \tau_{yy} - w \tau_{yz} \end{array} \right\} \quad H = \left\{ \begin{array}{l} \rho w \\ \rho u w - \tau_{zx} \\ \rho v w - \tau_{zy} \\ \rho w^2 + P - \tau_{zz} \\ \rho \left(e + \frac{V^2}{2} \right) w + P w - k \frac{\partial T}{\partial z} - u \tau_{zx} - v \tau_{zy} - w \tau_{zz} \end{array} \right\}$$

$$J = \left\{ \begin{array}{l} 0 \\ \rho f_x \\ \rho f_y \\ \rho f_z \\ \rho (u f_x + v f_y + w f_z) + \rho \dot{q} \end{array} \right\}$$



**Οι προς επίλυση διαφορικές εξισώσεις διατήρησης είναι πέντε:
Διατήρηση μάζας (1), διατήρηση ορμής (3), διατήρηση ενέργειας (1).**

Το σύστημα των εξισώσεων διατήρησης έχει πέντε διαφορικές εξισώσεις με έξι αγνώστους (ρ , u , v , w , p , T). Η εσωτερική ενέργεια e του ρευστού εκφράζεται με μία εξίσωση της μορφής

$e = e(p, T)$ που για αέρια απλοποιείται στην $e = C_V T$ με C_V την ειδική θερμότητα του αερίου υπό σταθερό όγκο και T τη θερμοκρασία του αερίου.

Τέλος η πίεση, η πυκνότητα και η θερμοκρασία συνδέονται με την καταστατική εξίσωση $\rho = \rho(p, T)$ που για αέρια παίρνει τη γνωστή μορφή

$$\frac{P}{\rho} = R T$$



Εκφράσεις των ΔΕ διατήρησης σε άλλα ορθογώνια συστήματα συντεταγμένων

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Μετασχηματισμός συντεταγμένων

Έστω καρτεσιανό σύστημα συντεταγμένων (x_1, x_2, x_3) και u_1, u_2, u_3 ένα καμπυλόγραμμο σύστημα. Μεταξύ των δύο συστημάτων υπάρχει η μονοσήμαντη σχέση μετασχηματισμού

$$x_i = x_i(u_1, u_2, u_3) \quad (i = 1, 2, 3)$$

Ένα διαφορικό σύστημα μήκους ds στο καρτεσιανό σύστημα εκφράζεται $ds^2 = dx_1^2 + dx_2^2 + dx_3^2$. Ένα διαφορικό μήκος dx_i κατά μήκος του άξονα x_i εκφράζεται ως συνάρτηση των καμπυλόγραμμων ορθογωνίων συντεταγμένων

$$dx_i = \frac{\partial x_i}{\partial u_j} du_j$$

Συνεπώς το διαφορικό μήκος ds εκφράζεται ως

$$ds^2 = \left(\frac{\partial x_1}{\partial u_j} du_j \right)^2 + \left(\frac{\partial x_2}{\partial u_k} du_k \right)^2 + \left(\frac{\partial x_3}{\partial u_\ell} du_\ell \right)^2$$



Μετασχηματισμός συντεταγμένων

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Επειδή όμως το καμπυλόγραμμο σύστημα συντεταγμένων είναι ορθογώνιο τότε το μεικτό γινόμενο θα είναι μηδέν, προκύπτει

$$ds^2 = \left(\frac{\partial x_i}{\partial u_1} \right)^2 du_1^2 + \left(\frac{\partial x_j}{\partial u_2} \right)^2 du_2^2 + \left(\frac{\partial x_k}{\partial u_3} \right)^2 du_3^2$$

(i, j, k βουβοί δείκτες)

$$ds^2 = \alpha_1^2 (du_1)^2 + \alpha_2^2 (du_2)^2 + \alpha_3^2 (du_3)^2$$

$$\text{όπου } \alpha_k = \sum_{i=1}^3 \left(\frac{\partial x_i}{\partial u_k} \right)^2 = \left(\frac{\partial x_1}{\partial u_k} \right)^2 + \left(\frac{\partial x_2}{\partial u_k} \right)^2 + \left(\frac{\partial x_3}{\partial u_k} \right)^2$$



Έκφραση ανάδελτα

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Στο καμπυλόγραμμο σύστημα ορθογωνίων συντεταγμένων u_1, u_2, u_3 , η διανυσματική σχέση

$$\nabla \cdot [K(x) \cdot \nabla] = \frac{1}{\alpha_1 \alpha_2 \alpha_3} \sum_{K=1}^3 \frac{\partial}{\partial u_K} \left[\frac{\alpha_1 \alpha_2 \alpha_3}{\alpha_K^2} K(u_1 u_2 u_3) \frac{\partial}{\partial u_K} \right]$$

και για K σταθερό

$$\nabla^2 = \frac{1}{\alpha_1 \alpha_2 \alpha_3} \sum_{K=1}^3 \frac{\partial}{\partial u_K} \left(\frac{\alpha_1 \alpha_2 \alpha_3}{\alpha_K^2} \frac{\partial}{\partial u_K} \right)$$



Κυλινδρικό σύστημα συντεταγμένων

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(α) Για κυλινδρικό σύστημα συντεταγμένων

$$x = r \cos \varphi, \quad y = r \sin \varphi, \quad z = z$$

τότε

$$\alpha_r^2 = \left(\frac{\partial x}{\partial r} \right)^2 + \left(\frac{\partial y}{\partial r} \right)^2 + \left(\frac{\partial z}{\partial r} \right)^2 = \cos^2 \varphi + \sin^2 \varphi = 1$$

$$\alpha_\varphi^2 = \left(\frac{\partial x}{\partial \varphi} \right)^2 + \left(\frac{\partial y}{\partial \varphi} \right)^2 + \left(\frac{\partial z}{\partial \varphi} \right)^2 = (-r \sin \varphi)^2 + (r \cos \varphi)^2 + 0 = r^2$$

$$\alpha_z^2 = \left(\frac{\partial x}{\partial z} \right)^2 + \left(\frac{\partial y}{\partial z} \right)^2 + \left(\frac{\partial z}{\partial z} \right)^2 = 0 + 0 + 1 = 1$$

Οπότε:

$$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial \varphi^2} + \frac{\partial^2}{\partial z^2}$$



Σφαιρικό σύστημα συντεταγμένων

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(β) Για σφαιρικό σύστημα συντεταγμένων

$$x = r \sin \theta \cos \varphi, \quad y = r \sin \theta \sin \varphi, \quad z = r \cos \theta$$

$$\alpha_r = 1, \quad \alpha_\varphi = r \sin \theta, \quad \alpha_\theta = r$$

$$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}$$



A general form of the equation

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Cartesian velocities-Cartesian coordinates
Nearly all equations are of the form

$$\frac{\partial}{\partial t}(\rho\Phi) + \frac{\partial}{\partial x_j} \left(\rho U_j \Phi - \Gamma_\Phi \frac{\partial \Phi}{\partial x_j} \right) = S_\Phi$$

Characteristics

multidimensional

turbulent flows require at least 6 equations

strong coupling

non-linear

$$\Phi = U_i, H, c, k, \varepsilon, \Gamma_\phi, S_\phi$$



Source Terms S_Φ

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$-\ddot{O}-$	$-S_{\ddot{O}}-$
1	0
u	$-\frac{\partial P}{\partial x} + \frac{\partial}{\partial x} \left(\mu \frac{\partial u}{\partial x} \right) + \frac{1}{r} \frac{\partial}{\partial r} \left(r \mu \frac{\partial v}{\partial x} \right)$
v	$-\frac{\partial P}{\partial r} - \frac{2\mu v}{r^2} + \frac{\partial}{\partial x} \left(\mu \frac{\partial u}{\partial r} \right) + \frac{1}{r} \frac{\partial}{\partial r} \left(r \mu \frac{\partial v}{\partial r} \right)$
$\hat{O}$	0
k	$G - \tilde{n} \dot{\alpha}$
$\dot{\alpha}$	$(C_1 \dot{\alpha} G - C_2 \tilde{n} \dot{\alpha}^2)/k$
	$G = \mu \left\{ 2 \left[\left(\frac{\partial u}{\partial x} \right)^2 + \left(\frac{\partial v}{\partial r} \right)^2 + \left(\frac{v}{r} \right)^2 \right] + \left(\frac{\partial u}{\partial r} + \frac{\partial v}{\partial x} \right)^2 \right\}$



Classification of flow phenomena

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Steady , **unsteady**
Incompressible , **compressible**
2D , **3D**

General form of PDE

$$A\Phi_{xx} + 2B\Phi_{xy} + C\Phi_{yy} + D\Phi_x + E\Phi_y + F\Phi = G$$

Where A,B,C,D,E,F and G functions of $x, y, \Phi, \Phi_x, \Phi_y$

$$B^2 - AC = <, 0, >$$

- Parabolic,
- elliptic,
- hyperbolic,
- partially elliptic

directional transport of information

type of boundary conditions



- **Heat Conduction**
- **Boundary layers**
- **Recirculating flows**
- **Supersonic flows**
- **Time dependent problems**
 - **Boundary value problems**
 - **Initial value problems**



Starting steps

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outline of the engineering problem

select dependent variables

select coordinate system

write down transport equations

**write down boundary conditions (well posed
mathematical problem)**

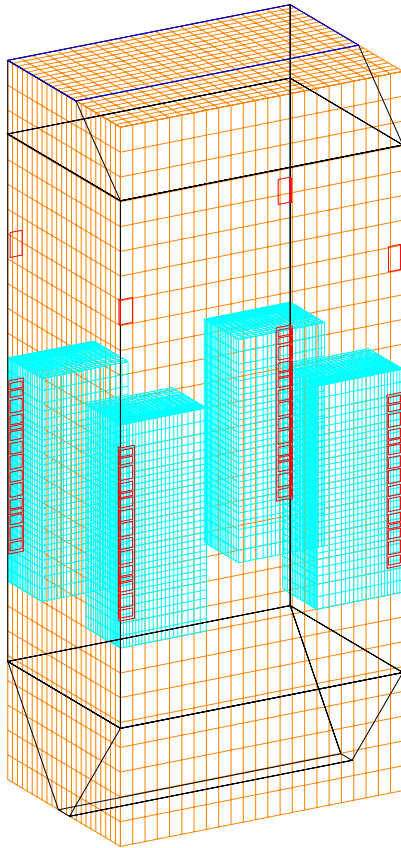
non-dimensionalize if possible



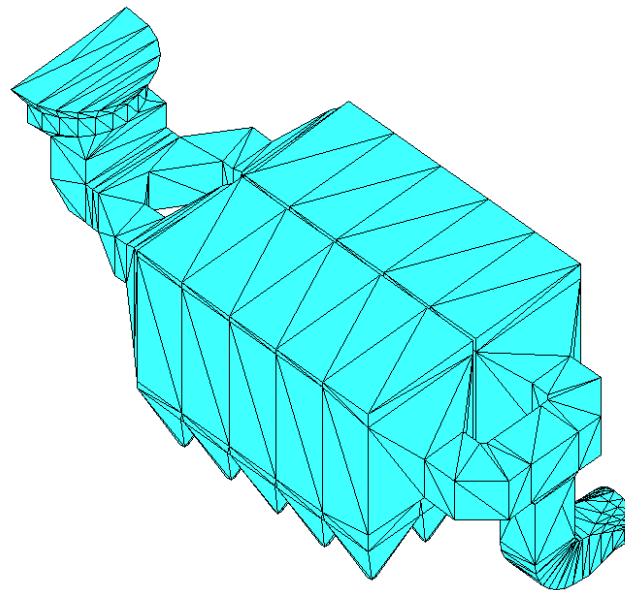


Examples of grids and dependent variables

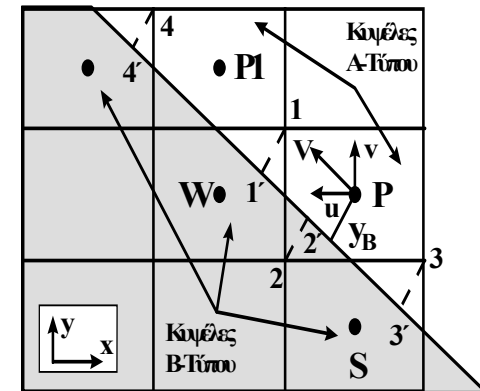
30



Boiler geometry



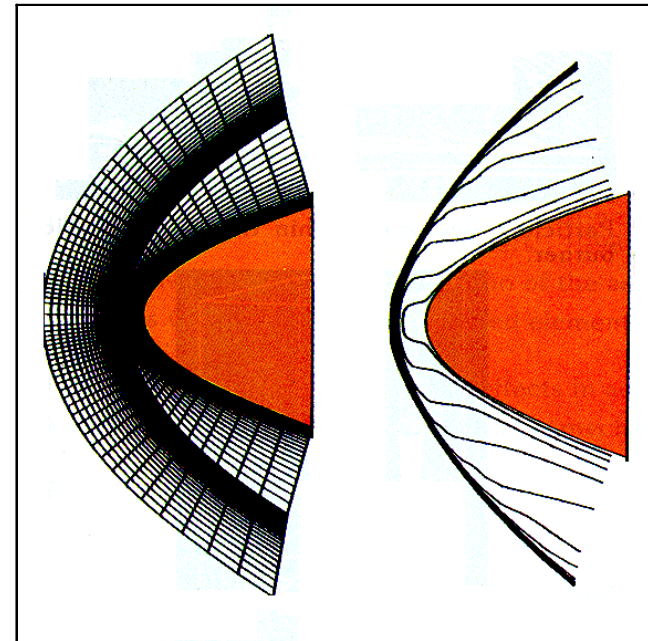
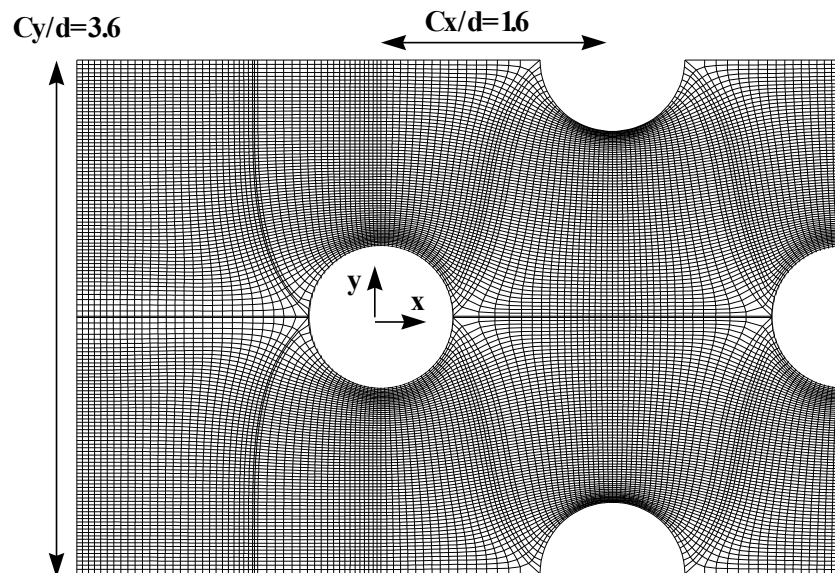
E/P geometry





Examples of grid/2

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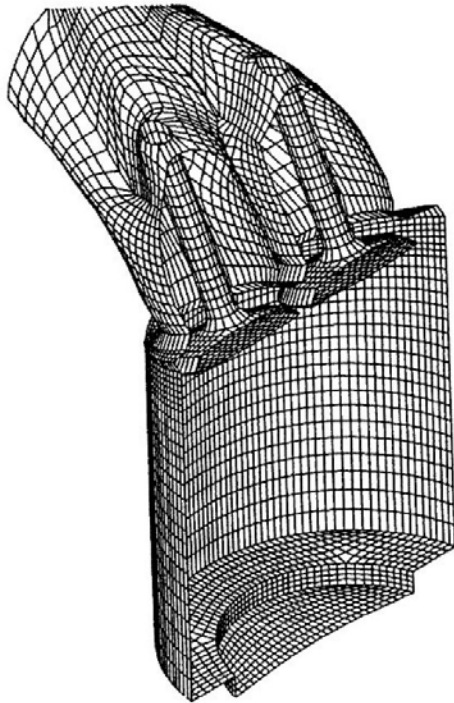




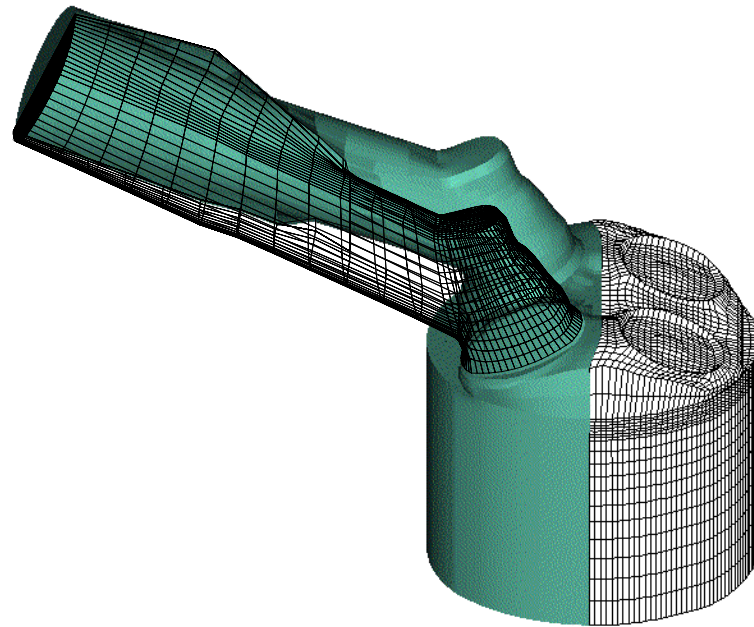
Examples of grid/3

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The intake port (UP Valencia)



An I.C engine



A graphics package is a must



Solution of a Poisson equation with Dirichlet or Neumann boundary conditions-forcing functions

"A Laplacian Equation Method for Numerical Generation of Boundary-fitted 3D Orthogonal Grids"

T.Theodoropoulos, G. C. Bergeles

Journal of Computational Physics, vol. 82,No 2,1989,pp269-288

"Numerical Grid Generation Technique for 3D Complex Spaces"

Glekas, J., Bergeles, G., Athanassiades, N.

3rd Intern. Conference, Computational Methods and Experimental measurements, Sept 1986,Porto Carras,Springer Verlag,Vol 2,pp905-916